

9.1 Search Terms

A number of terms and planning factors must be understood when planning and executing search and rescue missions.

Ground Track - an imaginary line on the ground that is made by an aircraft's flight path over the ground.

Maximum Area of Possibility - this normally circular area is centered at the missing airplane's (or search objective's) last known position (LKP), corrected for the effect of wind. The circle's radius represents the maximum distance a missing aircraft might have flown based on estimated fuel endurance time and corrected for the effects of the wind over that same amount of time. The radius may also represent the maximum distance survivors might have traveled on foot, corrected for environmental or topographical conditions, such as snow, wind, mountains, and rivers.

- *Meteorological Visibility* - the maximum distance at which large objects, such as a mountain, can be seen.

Probability Area - this is a smaller area, within the maximum possibility area, where, in the judgment of the incident commander or planner, there is an increased likelihood of locating the objective aircraft or survivor. Distress signals, sightings, radar track data, and the flight plan are typical factors that help define the probability area's boundaries.

Probability of Detection - the likelihood, expressed in a percent, that a search airplane might locate the objective. Probability of detection (POD) can be affected by weather, terrain, vegetation, skill of the search crew, and numerous other factors. When planning search missions, it is obviously more economical and most beneficial to survivors if we use a search altitude and track spacing that increases POD to the maximum, consistent with the flight conditions, team member experience levels, and safety. Note: POD will be decreased if only one scanner is on board and the search pattern is not adjusted accordingly.

Scanning Range - the lateral distance from a scanner's search aircraft to an imaginary line on the ground parallel to the search aircraft's ground track. Within the area formed by the ground track and scanning range, the scanner is expected to have a good chance at spotting the search objective. Scanning range can be less than but never greater than the search visibility.

Search Altitude - this is the altitude that the search aircraft flies above the ground (AGL). [Remember, routine flight planning and execution deals in MSL, while searches and assessments are referenced to AGL.]

Search Track - an imaginary swath across the surface, or ground. The scanning range and the length of the aircraft's ground track forms its dimensions.

Search Visibility - the distance at which an object on the ground (CAP uses an automobile as a familiar example) can be seen and recognized from a given height above the ground. Search visibility is always less than meteorological visibility. [Note that on the POD chart that the maximum search visibility listed is four nautical miles.]

Track Spacing - the distance (S) between adjacent ground tracks. The idea here is for each search track to either touch or slightly overlap the previous one. It is the pilot's task to navigate so that the aircraft's ground track develops proper track spacing.